## AGV Motion Driving Solution Slim Motor Rotation Module Drive Driving Wheel Jacking Module Slim Motor Integrated Motor Wheel Edge Planetary Gearbox **MOONS'** moving in better ways

## **COMPANY PROFILE**



Founded in 1994, MOONS' has grown to be a leading manufacturer of integrated motion control products, intelligent lighting products, and intelligent management systems. MOONS' is dedicated to providing its customers with system level solutions and continuously keeps the way to pursue innovation and high quality.

So far MOONS' has had a worldwide presence with sales, R&D or manufacturing sites in the United States, Europe, Japan, and Southeast Asia. There are more than 4,000 employees today in MOONS' who are committed to providing the best solutions to meet all customers' needs.

On May 9th 2017, MOONS' entered the capital market and was listed on the Shanghai Stock Exchange. Since then, MOONS' began to leverage these additional resources to widely expand its offerings and make all efforts to move in better ways.

moving in better ways

**MSD Driving Wheel** 

Nowadays, factory/warehouse/logistics are developing quickly in unmanned & robotized direction.

So Moons' is actively cooperating to **provide whole motion driving solutions for AGV/AMR/ACR...etc.** 

## Whole motion driving solution for latent jacking (floor) AGV:

## MSD Driving Wheel

<b>MSD160</b>	—	10	—	075 –	20	G	SL –	Ν	**	
<u>(1)</u>		$\widehat{(2)}$		(3)	<u>(4)</u>	(5)	<u>(6)</u>	$\overline{(7)}$	(8)	

- (1) MSD O.D.: 125/150/160/180/200/230/250 (Unit: mm)
- 2 Gear Ratio: 10/16/20/32
- ③ Power: 075—750W, 100—1000W etc.
- (4) Rated Speed: 20—2000rpm, 30—3000rpm etc.
- 5 Winding Voltage: G—DC48V, J—DC24V
- 6 Encoder: SL—Single Encoder, EL—Dual Encoders
- ⑦ Brake: N—Without, B—With
- 8 \*\*: Customized Code

## MBDV DRIVE

## JACKING & ROTATING MOTOR



## MSD150-10-040-20GSL-N/B

## MSD Specifications

O.D. of wheel \ width of wheel	mm	150 \ 36
Max. radial load of wheel		455
	kg	400
Speed at max. load	m/s	1.6
Peak speed at no load	m/s	2.4
Gearbox ratio		10
Basic DC bus voltage	V(DC)	48
Rated output power	Watts	400
Rated speed	rpm	2000
Rated torque	Nm	1.91
Peak torque	Nm	4.78
Rated current	A (rms)	11.4
Peak current	A (rms)	27.8
Brake	N/A (Optional)	
Encoder feedback	16-bit In	cremental magnetic encoder
Wheel characteristics	material	polyrethane or customization





#### MBDV Specifications

Voltage (VDC)	24~60		
Output continuous current (A rms)	20		
Output peak current (A rms)	60		
Safety function	STO, Dynamic brake, Emergency stop		
Dimensions	Refer to page 15 for details		

Driving Control

## Torque Curves



#### Dimensions (Unit: mm)





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Without Brake	L
MSD150-10-040-20GSL-N	146

## Gearbox Specifications

Ratio	10
Back lash	≤15arc
Rated torque	90N.m
Max. acceleration torque	162N.m
Emergency stop torque	270N.m
Efficiency	97%







With Brake	L
MSD150-10-040-20G	SL-B 172.5

## MSD160-10-075-20GSL-N/B

## MSD Specifications

[		
O.D. of wheel \ width of wheel	mm	160 \ 36
Max. radial load of wheel	kg	455
Speed at max. load	m/s	1.7
Peak speed at no load	m/s	2.1
Gearbox ratio		10
Basic DC Bus Voltage	V(DC)	48
Rated output oower	Watts	750
Rated speed	rpm	2000
Rated torque	Nm	3.6
Peak torque	Nm	7.2
Rated current	A (rms)	16.1
Peak current	A (rms)	32.7
Brake	N/A (Optional)	
Encoder feedback	16-bit In	cremental magnetic encoder
Wheel characteristics	material	polyrethane or customization





#### MBDV Specifications

Voltage (VDC)	24~60		
Output continuous current (A rms)	20		
Output peak current (A rms)	60		
Safety function	STO, Dynamic brake, Emergency stop		
Dimensions	Refer to page 15 for details		

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## Torque Curves



#### Dimensions (Unit: mm)



Without Brake	L
MSD160-10-075-20GSL-N	136



Ratio	10
Back lash	≤15arc
Rated torque	90N.m
Max acceleration torque	162N.m
Emergency stop torque	270N.m
Efficiency	97%



With Brake	L
MSD160-10-075-20GSL-B	156

## MSD180-10-075-20GSL-N/B

## MSD Specifications

		1001 17 5	
O.D. of wheel \ width of wheel	mm	180 \ 47.5	
Max. radial load of wheel	kg	625	
Speed at max. load	m/s	1.9	
Peak speed at no load	m/s	2.4	
Gearbox ratio		10	
Basic DC bus voltage	V(DC)	48	
Rated output power	Watts	750	
Rated speed	rpm	2000	
Rated torque	Nm	3.6	
Peak torque	Nm	7.2	
Rated current	A (rms)	16.1	
Peak current	A (rms)	32.7	
Brake		N/A (Optional)	
Encoder feedback	16-bit In	cremental magnetic encoder	
Wheel characteristics	material	polyrethane or customization	





#### MBDV Specifications

Voltage (VDC)	24~60
Output continuous current (A rms)	20
Output peak current (A rms)	60
Safety function	STO, Dynamic brake, Emergency stop
Dimensions	Refer to page 15 for details

Driving Control

10

≤15arc

95N.m

171N.m

285N.m

97%

3\*SV3.5-4

## MSD Driving Wheel

#### Torque Curves



#### Dimensions (Unit: mm)



			Y	47.5	1000±50
<u>4-M8</u>	 ¢	1 1	Ā Y		,

With Brake	L
MSD180-10-075-20GSL-B	168

Max. acceleration torque	
Emergency stop torque	
Efficiency	

Gearbox Specifications

Ratio

Back lash Rated torque



Without Brake	L
MSD180-10-075-20GSL-N	148

## MSD180-10-100-20GSL-N/B

## MSD Specifications

O.D. of wheel \ width of wheel	mm	180 \ 47.5
Max. radial load of wheel	kg	625
Speed at max. load	m/s	1.9
Peak speed at no load	m/s	2.4
Gearbox ratio		10
Basic DC bus voltage	V(DC)	48
Rated output power	Watts	1000
Rated speed	rpm	2000
Rated torque	Nm	4.8
Peak torque	Nm	7.2
Rated current	A (rms)	24.2
Peak current	A (rms)	35.1
Brake	N/A (Optional)	
Encoder feedback	16-bit Incremental magnetic encoder	
Wheel characteristics	material	polyrethane or customization





#### MBDV Specifications

Voltage (VDC)	24~60		
Output continuous current (A rms)	20		
Output peak current (A rms)	60		
Safety function	STO, Dynamic brake, Emergency stop		
Dimensions	Refer to page 15 for details		





#### Dimensions (Unit: mm)



Ratio	10
Back lash	≤15arc
Rated torque	95N.m
Max. acceleration torque	171N.m
Emergency stop torque	285N.m
Efficiency	97%

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1000±50

1000±50

3\*SV3.5-4



With Brake	L
MSD180-10-100-20GSL-B	207.5



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Without Brake	L
MSD180-10-100-20GSL-N	161

## MSD200-10-100-20GSL-N/B

## MSD Specifications

		2021 17 5
O.D. of wheel \ width of wheel	mm	200 \ 47.5
Max. radial load of wheel	kg	625
Speed at max. load	m/s	2.1
Peak speed at no load	m/s	2.6
Gearbox ratio		10
Basic DC bus voltage	V(DC)	48
Rated output power	Watts	1000
Rated speed	rpm	2000
Rated torque	Nm	4.8
Peak torque	Nm	7.2
Rated current	A (rms)	24.2
Peak current	A (rms)	35.1
Brake	N/A (Optional)	
Encoder feedback	16-bit Incremental magnetic encoder	
Wheel characteristics	material	polyrethane or customization





#### MBDV Specifications

Voltage (VDC)	24~60		
Output continuous current (A rms)	20		
Output peak current (A rms)	60		
Safety function	STO, Dynamic brake, Emergency stop		
Dimensions	Refer to page 15 for details		

## Torque Curves



## Dimensions (Unit: mm)







Without Brake	L
MSD200-10-100-20GSL-N	161



Ratio	10
Back lash	≤15arc
Rated torque	95N.m
Max. acceleration torque	171N.m
Emergency stop torque	285N.m
Efficiency	97%

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With Brake	L
MSD200-10-100-20GSL-B	207.5

## MBDV DRIVE



## MBDV Specifications

Voltage (VDC)	24~60	
Control mode	<ul> <li>CANopen communication control mode</li> <li>Complicate with CiA402 standard and supports PP, PV, PVT,TQ and HM mode</li> <li>Modbus/RTU communication control mode</li> <li>Command position mode, command speed mode, command torque mode</li> </ul>	
Dynamic braking	Built in	
STO	STO compliant with *SIL3 Level	
Certification	RoHS、CE、UL	

Note: \* Certification is pending



#### MBDV-2X-520AC Size (Unit: mm)

#### MBDV-2X-520AC Interface Description



## MBDV-53SAC Size (Unit: mm)





#### MBDV-53SAC Interface Description



## **JACKING & ROTATING MOTOR**

#### 60mm-Specifications

Model		SM0602GSL-KCY-NNV-10	SM0602GSL-KCY-BNV-10
Basic DC bus voltage	V(DC)	48	48
Rated output power	Watts	400	400
Rated speed	rpm	3000	3000
Max. speed	rpm	4800	4800
Rated torque	Nm	1.27	1.27
Peak torque	Nm	3.8	3.8
Rated current	A (rms)	12.6	12.6
Peak current	A (rms)	38	38
Voltage constant $\pm 5\%$	V(rms)/K rpm	6.25	6.25
Torque constant $\pm 5\%$	Nm/A(rms)	0.103	0.103
Inertia	kg m <sup>2</sup>	0.566x10 <sup>-4</sup>	0.62x10 <sup>-4</sup>
Shaft load - axial	N (max.)	70	70
Shaft load - radial (end of shaft)	N (max.)	240	240
Brake		without	with
Gearbox option		N/A (optional)	
Encoder feedback		16-bit Incremental magnetic encoder	

#### Torque Curves

SM-60-400W DC Bus: 48VDC



#### Dimensions (Unit: mm)

#### Without Brake



With Brake



With Brake	L	
SM0602GSL-KCY-BNV-10	102.5	

## **JACKING & ROTATING MOTOR**

#### 80mm-Specifications

Model		SM0803GSL-KCY-NNV-10	SM0803GSL-KCY-BNV-10
Basic DC bus voltage	V(DC)	48	48
Rated output power	Watts	750	750
Rated speed	rpm	3000	3000
Max. speed	rpm	4000	4000
Rated torque	Nm	2.4	2.4
Peak torque	Nm	7.2	7.2
Rated current	A (rms)	19	19
Peak current	A (rms)	60	60
Voltage constant $\pm 5\%$	V(rms)/K rpm	7.75	7.75
Torque constant $\pm 5\%$	Nm/A(rms)	0.128	0.128
Inertia	kg m <sup>2</sup>	1.46x10 <sup>-4</sup>	1.63x10 <sup>-4</sup>
Shaft load - axial	N (max.)	90	90
Shaft load - radial (end of shaft)	N (max.)	270	270
Brake		without	with
Gearbox option		N/A (optional)	
Encoder feedback		16-bit Incremental magnetic encoder	

#### Torque Curves



#### Dimensions (Unit: mm)

#### Without Brake





Without Brake	L
SM0803GSL-KCY-NNV-10	78.4



With Brake	L
SM0803GSL-KCY-BNV-10	110.7

MOONS'









MOONS' has set up twelve offices in China, as well as subsidiaries in other countries including the United States, Italy, Singapore, Japan and Germany. Our business covers major countries and regions in North America, Europe, Asia and Southeast Asia ensure MOONS' close to where you are.

MOONS'

## Customer Service Center +86-400-820-9661

#### MOONS' Headquarter

168 Mingjia Road, Minhang District, Shanghai 201107, P.R. China

#### MOONS' Taicang

No. 18 Yingang Rd, Fuqiao Town, Taicang City Jiangsu Province, 215434, P.R. China

#### Domestic Office

#### Beijing

Room 1206, Jing Liang Mansion, No.16 Middle Road of East,3rd Ring, Chaoyang District, Beijing 100022, P.R. China

#### Qingdao

Room1913,Scientific and Technological Innovation Builing,Floor19, No.171, ShanDong Road,Shibei District,QingDao, Shangdong Province, 11 266033, P.R. China

#### Xi'an

Room 1006, Tower D, Wangzuo International City, No.1 Tangyan Road, Xi'an, Shanxi Province, 710065, P.R. China

#### Wuhan

Room 3001, World Trade Tower, No.686 Jiefang Avenue, Jianghan District, Wuhan, Hubei Province, 430022, P.R. China

#### Hefei

Room 1521, Building B, CBC Tuoji Plaza, Jinggang Road, Shushan District, Hefei, Anhui Province, 230088, P.R. China

#### Nanjing

Room 1101-1102, Building 2, New Town Development Center, No.126 Tianyuan Road, Moling Street, Jiangning District, Jiangsu Province, China, 211106, P.R. China

#### Suzhou

Room 1103-1105, North Building 4, Huizu Plaza, 758 Nanhuan East Rd, Gusu District, Suzhou, Jiangsu Province, 215007, P.R. China

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https://www.moonsindustries.com/

E-mail:ama-info@moons.com.cn

#### Ningbo

Room 309, Tower B, Taifu Plaza, 565 Jiangjia Road, Jiangdong District, Ningbo, Zhejiang Province, 315040, P.R. China

#### Chengdu

Room 3907, Maoye Plaza, No.19, Dongyu Street, Jinjiang Distrit, Chengdu Sichuan Province, 610066, P.R. China

#### Chongqing

Room 2108, South yuanzhu Buliding 20, No.18 Fuquan Rd., Jiangbei District, Chongqing, 400000, P.R. China

#### Guangzhou

Room 4006, Tower B, China Shine Plaza, 9 Linhe Xi Road, Tianhe District, Guangzhou, Guangdong Province, 510610, P.R. China

Dongguan

Room 1106-1207, Building 5, Linrunzhigu, No.1 RD 5th Rd, Songshan Lake, Dongguan, Guangdong Province, 523000, P.R. China

#### Shenzhen

Room 3901, Building A, Zhongguan Times Square,No 4168 Liuxian Avenue, Nanshan District, Shenzhen, Guangdong Province, 518000, P.R. China

#### North America

#### USA

MOONS' INDUSTRIES (AMERICA), INC. (Chicago) 1113 North Prospect Avenue, Itasca, IL 60143, USA

MOONS' INDUSTRIES (AMERICA), INC. (Boston) 36 Cordage Park Circle, Suite 310 Plymouth, MA 02360, USA

APPLIED MOTION PRODUCTS, INC. (Morgan Hill) 18645 Madrone Parkway. Morgan Hill, CA 95037, USA

LIN ENGINEERING, Inc. (Morgan Hill) 16245 Vineyard Blvd., Morgan Hill, CA 95037, USA



#### Italy

MOONS' INDUSTRIES (EUROPE) HEAD QUARTER S.R.L. Via Torri Bianche n.1 20871 Vimercate(MB) Italy

Germany

AMP & MOONS' AUTOMATION (GERMANY) GMBH Kaiserhofstr. 15 60313 Frankfurt am Main Germany

Switzerland TECHNOSOFT SA Avenue des Alpes 20

CH 2000 Neuchâtel Switzerland

MOONS' INDUSTRIES (UK), LIMITED Reading, Berkshire, UK

Asia

#### Singapore

MOONS' INDUSTRIES (SOUTH-EAST ASIA) PTE. LTD. 33 Ubi Avenue 3 #08-23 Vertex Singapore 408868

#### Japan

MOONS' INDUSTRIES JAPAN CO., LTD. Room 602, 6F, Shin Yokohama Koushin Building, 2-12-1, Shin-Yokohama, Kohoku-ku, Yokohama,Kanagawa, Japan 222-0033

#### India

MOONS' INTELLIGENT MOTION SYSTEM INDIA PVT. LTD. Room. 908, 9th Floor, Amar Business Park, Tal. Haveli, Baner, Pune, India 411045

#### Vietnam

MOONS' VIETNAM MANUFACTURING SITE

Factory C1&D1, Lot IN3-11\*A, VSIP Hai Phong Industrial Park in Dinh Vu – Cat Hai Economic Zone, Lap Le Commune, Thuy Nguyen District, Hai Phong City, Vietnam

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